

**THE GROUP OF RESPONSABLES "FLIGHT MECHANICS, SYSTEMS AND
INTEGRATION (GOR FM)":
AN OVERVIEW OF ACTIVITIES AND SUCCESS STORIES**

ICAS 2022, Stockholm

Bernd Korn (DLR) & Martin Hagström (FOI)

THE GROUP OF RESPONSABLES "FLIGHT MECHANICS, SYSTEMS AND INTEGRATION (GOR FM)": AN OVERVIEW OF ACTIVITIES AND SUCCESS STORIES

- **GoR FM – General Overview**
- **Some examples of GoR FM projects**
- **Outlook – what will we do**

GoR FM: Who we are!

Current members

Airbus (F): Philippe Goupil

Airbus (G): Martin Hanel

Dassault: Laurent Goerig

Saab: Peter Rosander

CIRA: Antonio Vitale

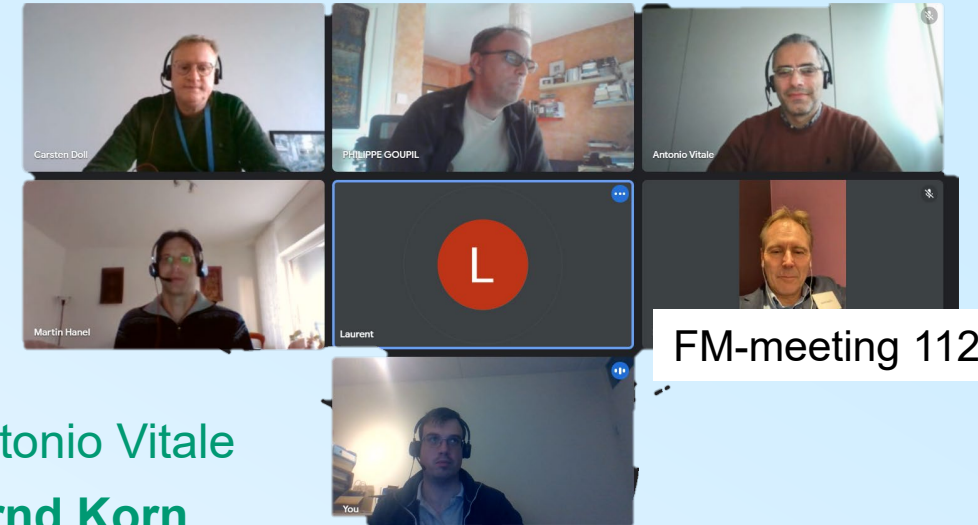
DLR: **Bernd Korn**

FOI: Martin Hagström

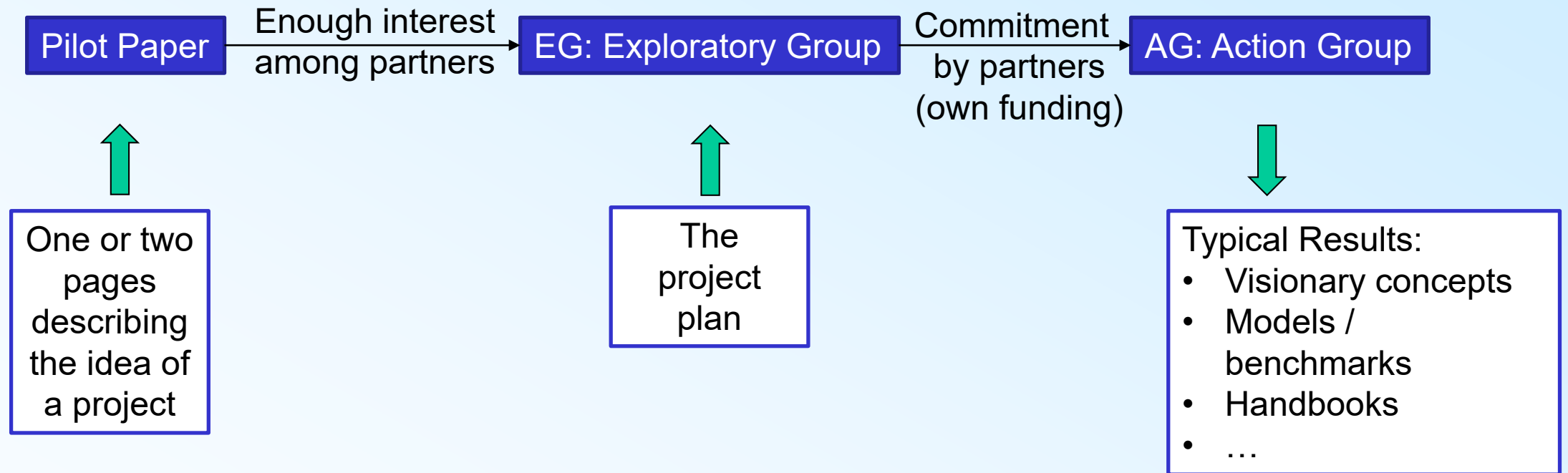
NLR: Marinus Johannus (Richard) van Enkhuizen

ONERA: ***Carsten Doll***

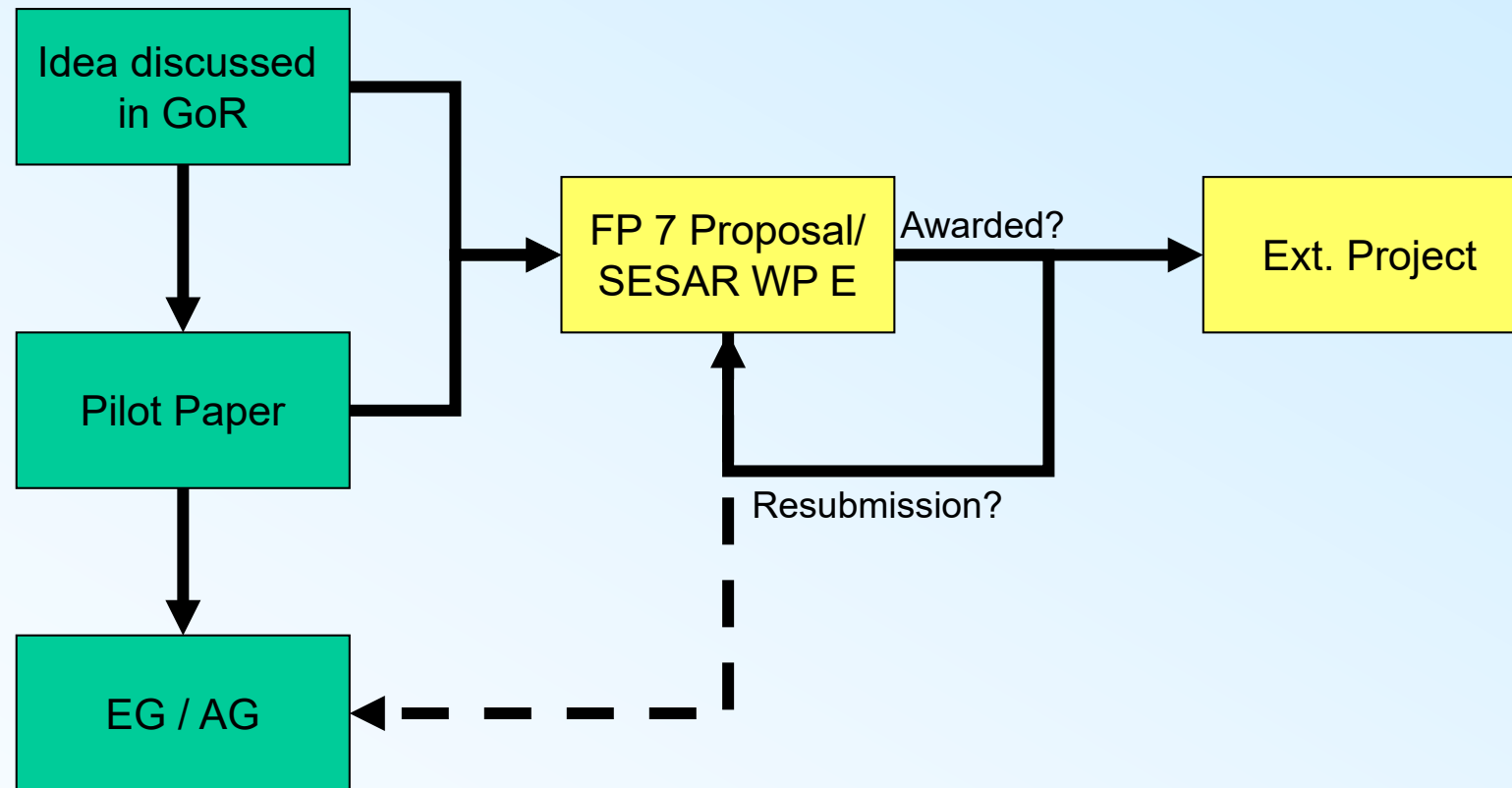
University of the Highlands and Islands
in Scotland & Ampaire: Andrew Rae



GoR FM: How do we work

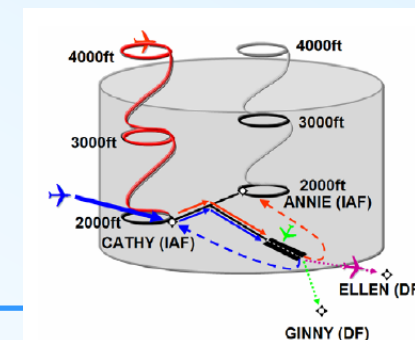
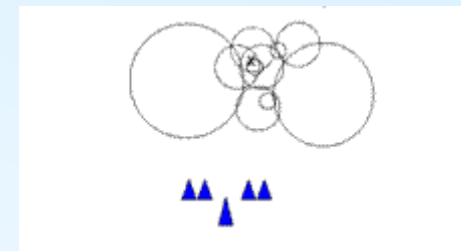
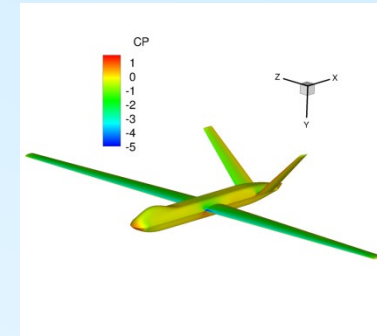


Lack of funding: GARTEUR activity or European Project?



GoR FM: Research Objectives

- A** *Development and benefit assessment of advanced methods for analysis and synthesis of flight control systems for aircraft with both conventional and non conventional aero structural configurations.*
- B** *Development of advanced methods for UAV mission automation*
- C** *Development and benefit assessment of advanced aircraft capabilities into ATM/ATC related applications*






















GoR FM: Research Activities

- More than 80 reports on Garteur website (<https://garteur.org>)

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Aerodynamics Aviation Security **Flight Mechanics, Systems and Integration** Helicopters Structures and Materials

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Ref	AG	Title	Authors	Date	Status	Download
TP-002	PM/EG-01	An analysis of the gaps and overlaps in the area of the major facilities for flight mechanics in the GARTEUR countries (2 volumes)	Collective	feb-81	L->O	 Download
TP-003	PM/AG-01	Handling qualities guidelines for future ACT transport aircraft	H.A. Mooij, D. Hanke, D.E. Fry, G. Leblanc	juil-82	L->O	 Download
TP-017	PM/AG-01	Design guidelines for handling qualities of future transport aircraft with active control technology	W.P. de Boer, M.F.C. van Gool, C. La Burthe, O.P. Nicholas, D. Schafranek	Apr 1984	L->O	 Download
TP-026	PM/AG-01	Test plan for the preliminary investigation in the ONERA Flight Mechanics Laboratory	W.P. de Boer, M.F.C. van Gool, C. La Burthe, O.P. Nicholas, D. Schafranek	mar-87	O	 Download
TP-027	PM/AG-01	Results of GARTEUR preliminary handling qualities investigations in the ONERA Flight Mechanics Laboratory	W.P. de Boer, J.A.J. van Engelen, C. la Burthe, H.T. Huynh, O.P. Nicholas, D. Schafranek	juil-88	O	 Download
TP-031	PM/AG-01	Test plan investigation on the NLR flight simulator concerning handling qualities of transport aircraft with advanced flight control and display systems	W.P. de Boer, C. La Burthe, M.F.C. van Gool, O.P. Nicholas, D. Schafranek, H.T. Huynh	Aug 1987	O	 Download
TP-051	PM/AG-01	Results of simulation experiments to establish handling qualities guidelines for the design of future transport aircraft	J.A.J. van Engelen	Aug 1988	O	#N/A
TP-055	PM/AG-01	Final report on a simulator study into low speed longitudinal handling qualities of ACT transport aircraft	W.P. de Boer, J.A.J. van Engelen, H.T. Huynh, O.P. Nicholas, D. Schafranek	juil-90	O	 Download
TP-056	PM/AG-01	Some longitudinal handling qualities design guidelines for active control technology transport aircraft	W.P. de Boer, J.A.J. van Engelen, H.T. Huynh, O.P. Nicholas, D. Schafranek	may-90	O	 Download
TP-023	PM/AG-02	Parameter identification of a wide bodied transport aircraft (results of Part 1) 7 3 volumes	B. Krag	Aug 1986	L->O	 Download
TP-087	PM/AG-02	Mathematical modelling of aircraft	Collective	sep-95	L->O	 Download
TP-024	PM/AG-03	A future air traffic management scenario	Collective	Apr 1987	O	 Download
TP-025	PM/AG-03	Integration of flight management and air traffic management systems	Collective	Apr 1987	O	 Download
TP-049	PM/AG-03	A conceptual model of a future integrated ATM System	Collective	Jan 1989	O	 Download
TP-050	PM/AG-03	Noval functional requirements for a future flight management system	Collective	Jan 1989	O	 Download
TP-057	PM/AG-03	Integration of flight management and air traffic management systems	Collective	feb-90	O	 Download
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TP-071	PM/AG-04	The Work of PM/AG04 on Phase I of a Lateral/Direction Handling Qualities Design Guidelines Study (Final Report)	J.J. Buchholz, H.T. Huynh, O.P. Nicholas, W.F. Rouwhorst, D. Schafranek	oct-94	O	#N/A
TP-073	PM/AG-05	A Review of Existing Windshear Models	K.U. Hahn (editor)	Apr 1994	O	 Download
TP-086	PM/AG-05	Windshear occurrences in Europe. Some annotated cases and inquiry into a windshear database	H. Haverdings et al.	juil-95	O	 Download

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November 2011/GARTEUR Secretary

*Area A:
Development and benefit
assessment of advanced
methods for analysis and
synthesis of flight control
systems for aircraft with both
conventional and non
conventional aero structural
configurations.*

GoR FM: Research Activities

- (iii) Resolution of conflicts more strategically, over longer time horizons.
- (iv) Improved en-route capacity through exploitation of more accurate three-dimensional (3-D) navigation, and use of longitudinal (ie time) navigation and control to increase capacity of junctions and terminal areas.

- (v) Improved accommodation of aircraft in terminal areas, based on computer simulation.

7 CONSTRAINTS AND GUIDELINES

These guidelines

- (i) Must maintain

*Area C:
Development and benefit
assessment of advanced aircraft
capabilities into ATM/ATC related
applications*

unaided. Poorly equipped aircraft might require assistance, particularly in terminal areas where the constraints would be more stringent.

dimensional
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tubes would
meteorological
ft would not
implies that
should be built

the clearance

GoR FM: Research Activities

- (a) The best model of the aircraft's performance, its costs and capabilities will reside in the aircraft's computers. One may deduce that the aircraft should propose a trajectory and possibly bid for a time slot.
- (b) The only viable model of the overall ATC situation is in the ATC system and its computers, therefore the ground based system should retain the overall adjudication, safety and optimisation functions. It must allocate slot times and trajectories and arbitrate between conflicting requirements.
- (c) Air and ground system should agree on the description of a partial or complete trajectory to ensure that it is practical and safe, which the aircraft must then execute.
- (d) The ground system should provide a monitoring function against significant deviations from these agreed trajectories.
- (e) Provision must be made for modification of this trajectory to cope with unexpected events.

see
SESAR activity on
initial 4D...

3.2.3 Description of Trajectories as Tubes in Space

In essence a 4D trajectory could be described as a line through 4D space. For practical reasons tolerances must be introduced and so the line becomes a tube. It can be imagined as a bubble moving through a tube such that its position as a function of time is known. It could also be regarded as an extension of today's separation standards which are defined in vertical, horizontal and longitudinal directions.

The bubble would have internal structure composed of three concentric regions. From the inside, these regions reflect the performance of aircraft navigation, ATC surveillance and any correction manoeuvre should an aircraft stray outside its agreed trajectory.

The three regions are defined as follows :

- manoeuvre space is the inner region. The aircraft is authorised to optimise its own trajectory within this space, subject only to remaining within this space. The minimum dimensions of manoeuvre space are determined by the aircraft's navigation accuracy.
- detection space, which surrounds manoeuvre space. It is there to allow the ATC surveillance process to detect that an aircraft has left its manoeuvre space. The minimum dimensions of detection space are determined by the accuracy of the surveillance system.

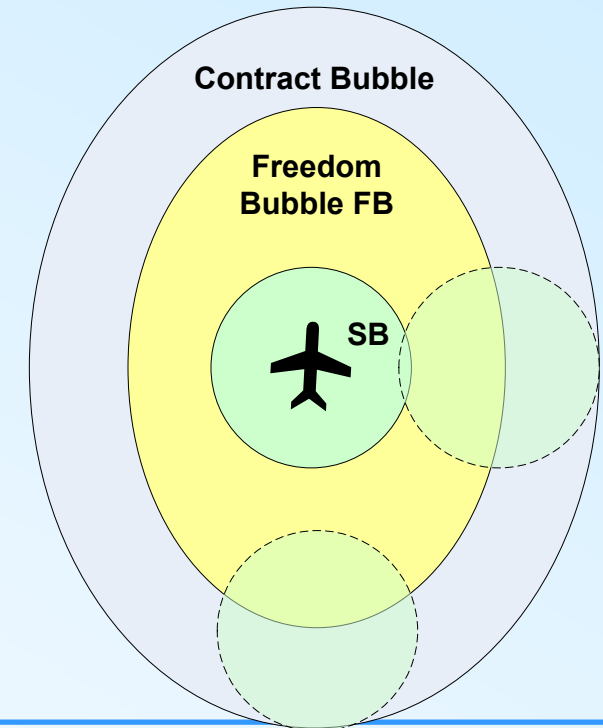
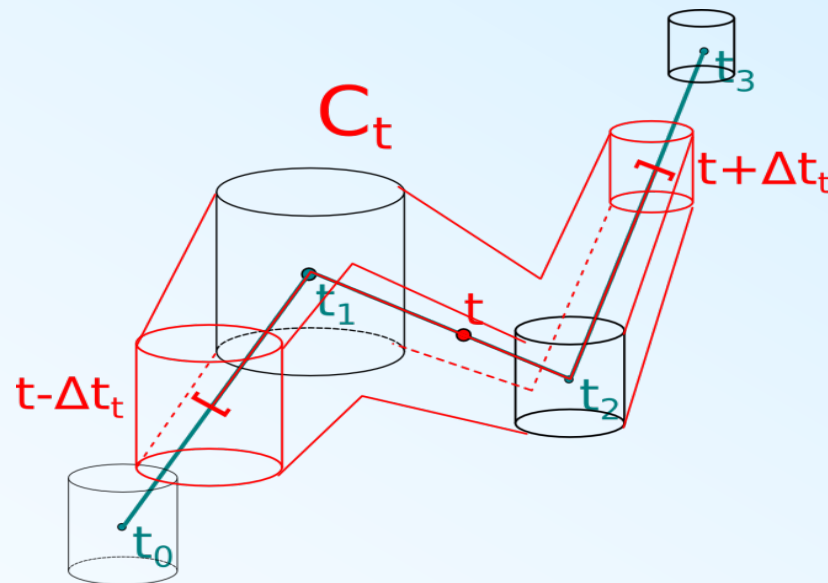
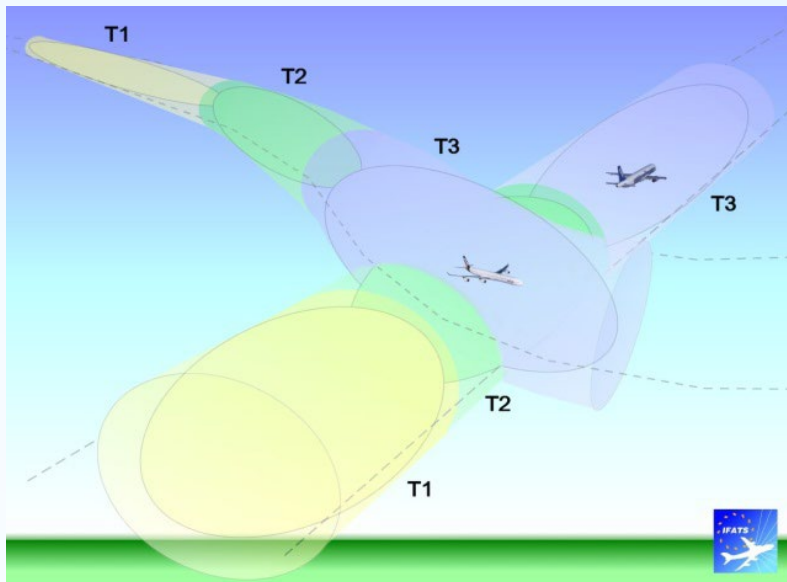
IN - SWEDEN - UNITED KINGDOM

Activities

From AG3 – Report on „A Conceptual Model of a Future Integrated ATM system“

European Project 4DCo-GC

Conflict free Contracts are assigned to A/C
A/C is responsible to stay within the contract
ATC monitors – is only active if contract is violated



European Project 4DCo-GC

4 Scenarios

Benelux - airspace

- Benelux 100% = 5297 flights
- Benelux 233% = 11925 flights

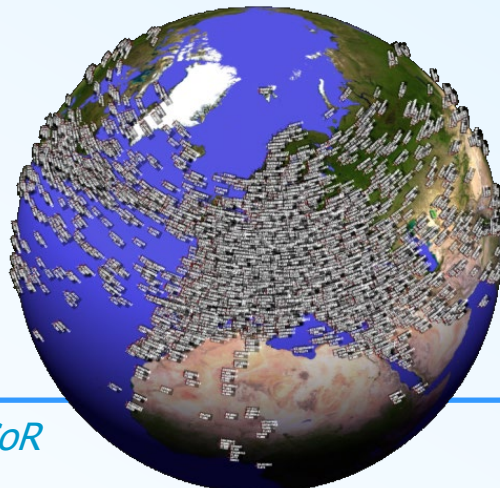
Separations:

6.0 NM/1000 ft above and in FL100

3.2 NM/1000 ft below FL100

3.0 NM safety

ECAC 233%



Scenario	Traffic	Event
S1	100% Benelux Traffic	~5 kts wind deviation between forecast and actual
S2	233% Benelux Traffic	~5 kts wind deviation between forecast and actual
S3	100% Benelux Traffic	Airport closure Luxembourg, replan to Brussels airport
S4	100% Benelux Traffic	Decompression, immediate decent, generating a conflict with another aircraft

AG17 “Non Linear Analysis and Synthesis Techniques for Aircraft Control”

Chairman: M. Hagström, FOI

Objectives:

- Application of modern non-linear methods for system analysis and control synthesis to aircraft control in an industrial setting. The goal is to identify and evaluate methods that are easy to use, accurate, reliable and time saving that can replace the traditional tools used in the aircraft industry for control synthesis and analysis today.

Achievements:

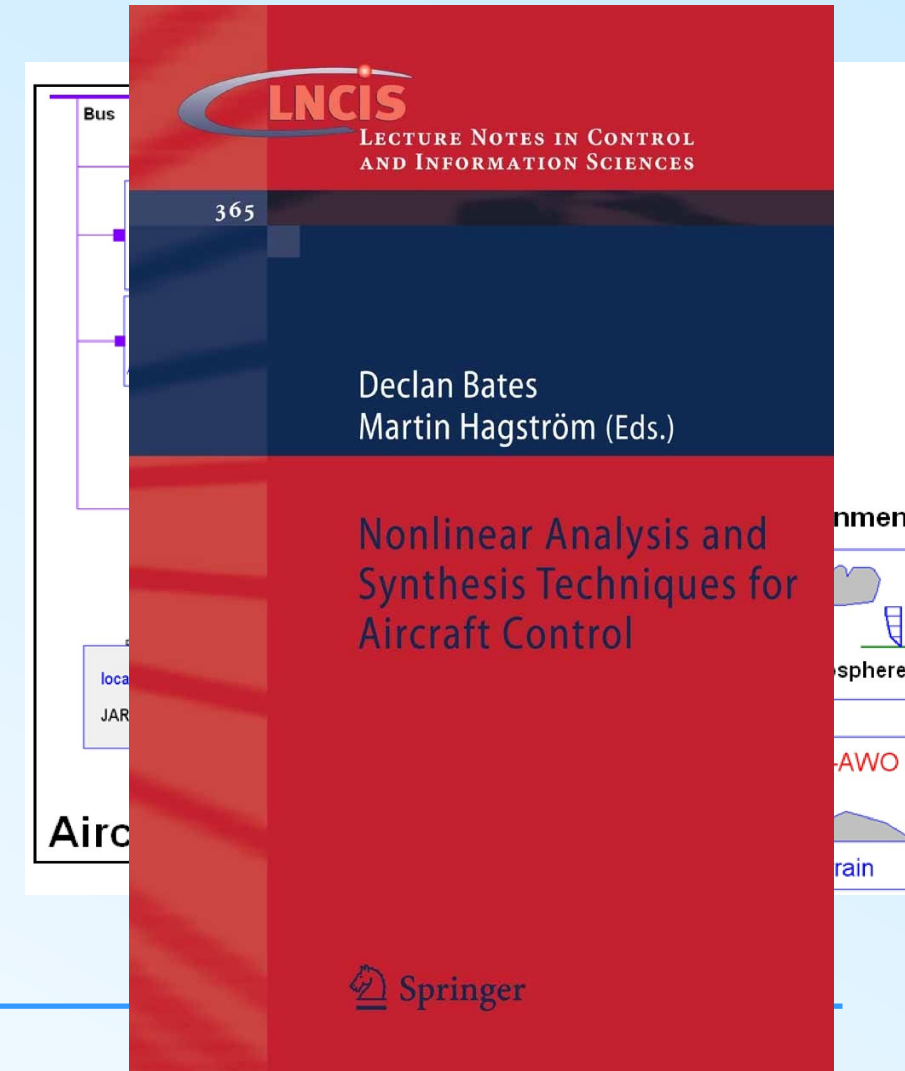
- ✓ The AG17 produce the first exhaustive set of results of advanced nonlinear control methods for complex models of aircrafts both civil and military
- ✓ Results published as book by Springer

AG17: Some more details

Developement of an on-ground transport aircraft benchmark
(simulation model + design challanges)

Application of nine different approaches and techniques to the benchmark problems:

- Nonlinear symbolic LFT tools for modelling, analysis and design
- Nonlinear LFT modelling for on-ground transport aircraft
- On-ground aircraft control design using an LPV anti-windup approach
- Rapid prototyping using inversion-based control and object-oriented modelling
- Robustness analysis versus mixed LTI/LTV uncertainties for on-ground aircraft
- An LPV Control Law Design and Evaluation for the ADMIRE Model
- Block Backstepping For Nonlinear Flight Control Law Design
- Optimisation-based flight control law clearance
- Investigation of the ADMIRE Manoeuvring Capabilities Using Qualitative Methods



FM/AG-18 'Towards greater Autonomy in Multiple Unmanned Air Vehicles'

Chairman: Dr Jon Platts, QinetiQ, UK

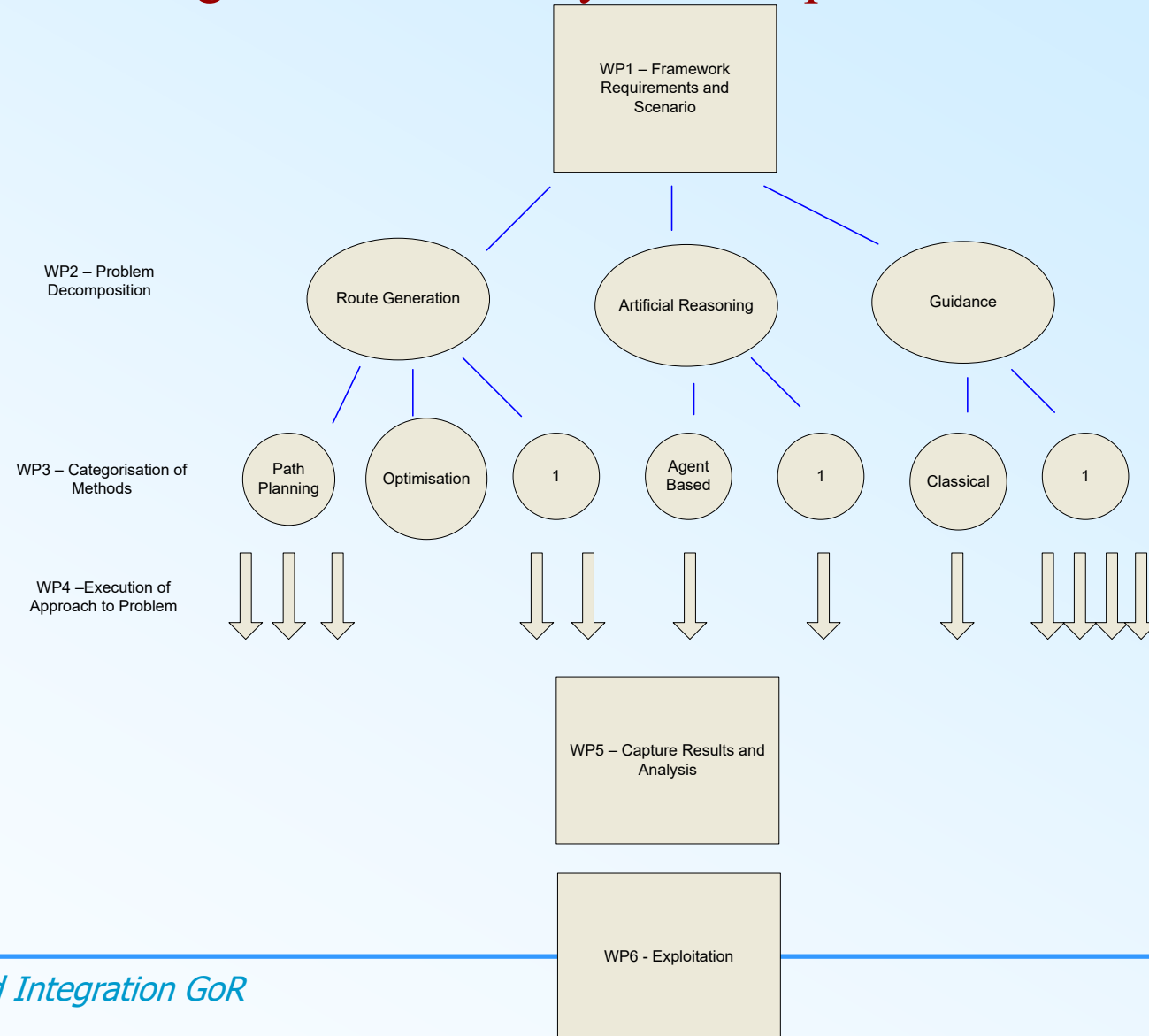
Objectives

- Use of machine based reasoning and artificial cognition
- To facilitate co-operation between UAV and other assets
- Reduced human intervention

Participation

- ✓ QinetiQ, ONERA, NLR, DLR, CIRA, INTA,
- ✓ University of Bristol, Universität der Bundeswehr München, Universidade Comptense Madrid, University of Leicester, University of Cranfield, University of Bristol
- ✓ Dassault Aviation, EADS Cassidian, EADS CASA, Thales NL

FM/AG-18 'Towards greater Autonomy in Multiple Unmanned Air Vehicles'

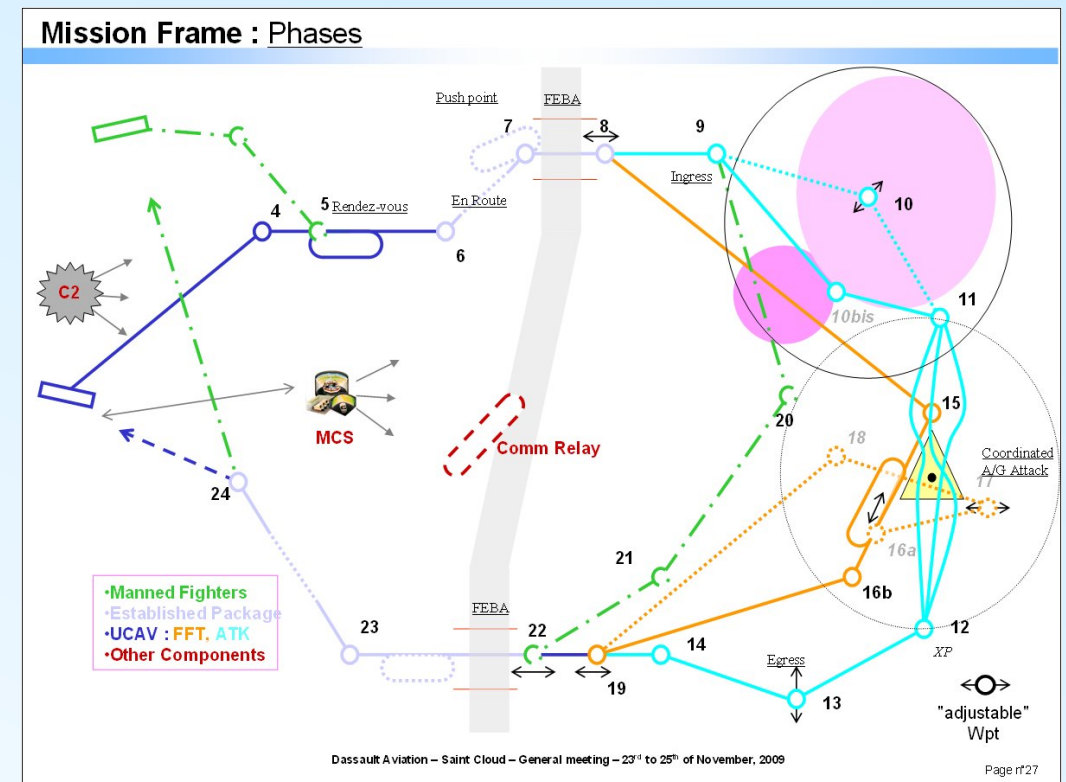


FM/AG-18 'Towards greater Autonomy in Multiple Unmanned Air Vehicles'

Candidate Methods:

- Real time trajectory generation and tracking algorithm for 4D autonomous navigation (CIRA)
- Nonlinear Branch and Bound for path planning with avoidance (Univ. Bristol)
- Dual-mode cognitive automation for guidance (BWh Univ. Munich)
- Evolutionary path planner for multiple UAV in realistic environments (Univ. Madrid + CASA)
- Trajectory generation and mission planning and optimization for multiple UAV (NLR)
- Dubins and PH curve path planning + behavior recognition and tracking by non-linear model predictive control on a receding horizon (Univ. Cranfield)
- Reactive and deliberative architecture with planning based on constraint satisfaction (ONERA + Dassault)
- Non Linear robust filtering and SLAM (Univ. Leicester)

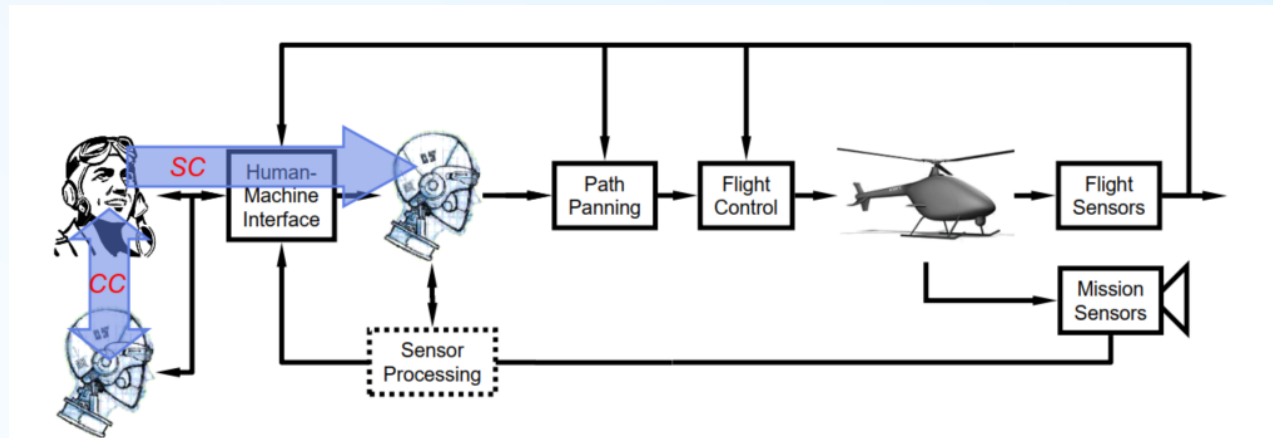
Global mission benchmark



FM/AG-18 'Towards greater Autonomy in Multiple Unmanned Air Vehicles'

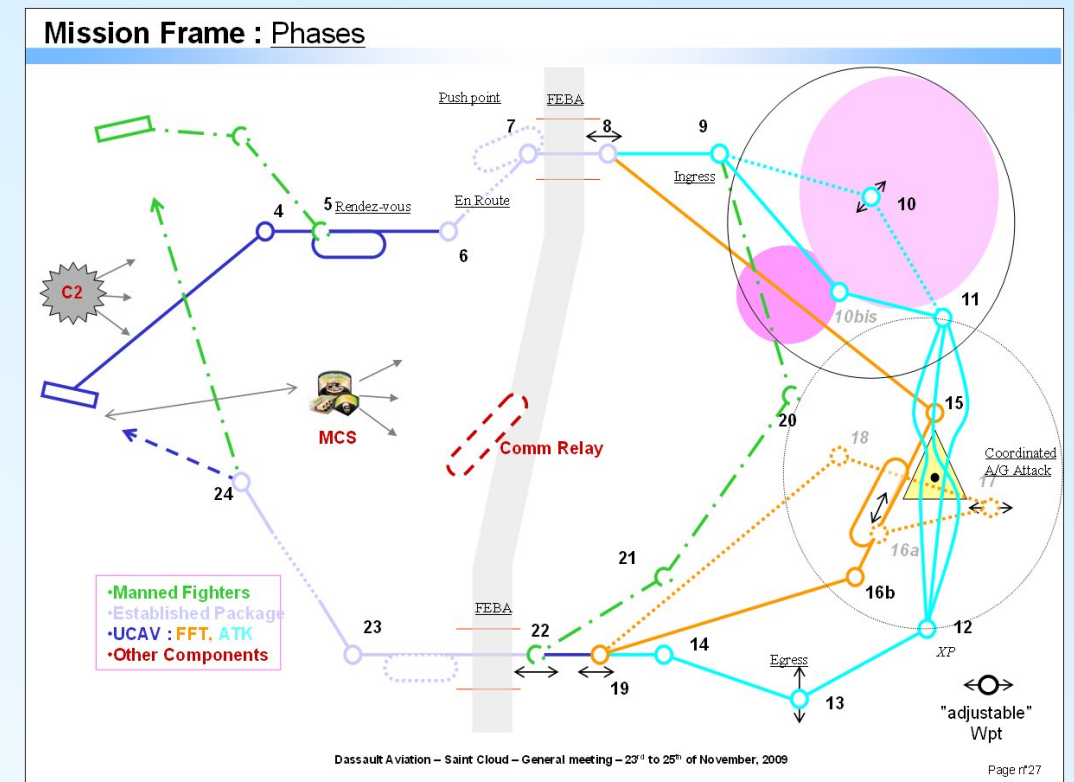
Example:

Universität der Bundeswehr München - Cognitive automation approaches to multi-UAV mission management

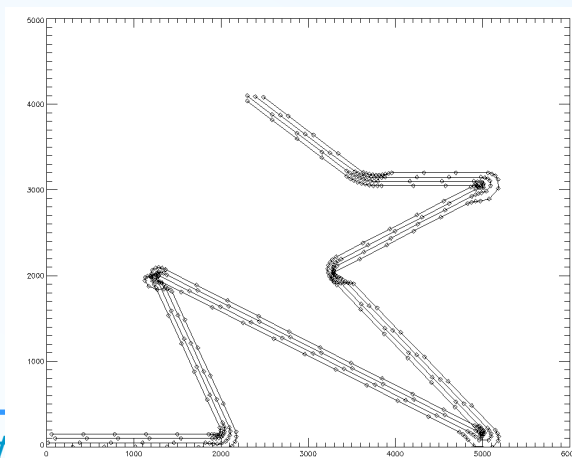
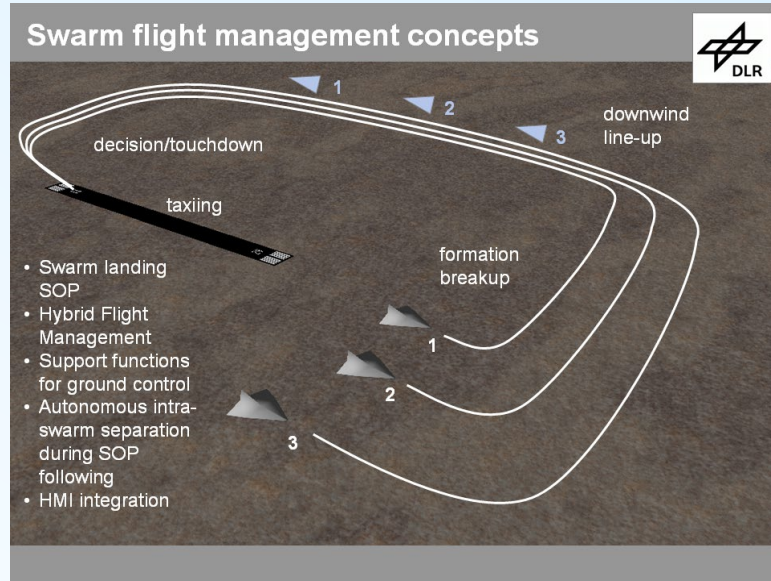


Integration of "Artificial Cognitive Units" allowing the human to switch between Supervisory Control (SC) of highly automated vehicle and Cooperative Control (CC) in which the human and the artificial cognitive agent work together like a cockpit crew

Global mission benchmark

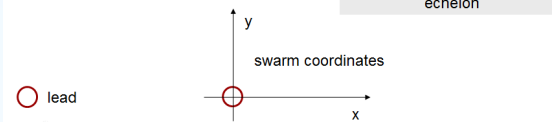


FM/AG-18 Example: DLR – formation management

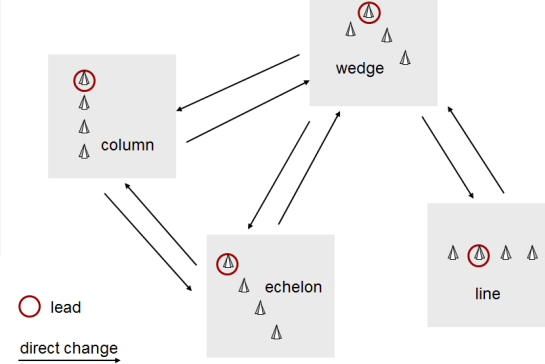


Formation data

```
n: 4
id_lead: 1
formation: 'echelon'
position: LIST(point2d)
b_stable: TRUE
formation_next: 'echelon'
b_transition: FALSE
b_dissolve: FALSE
b_assemble: FALSE
d_x: 60
d_y: 60
bounding box: [x1,x2,y1,y2]
rel_speeds: 10
rel_posxy_curr: array[n]
rel_posxy_next: array[n]
```



Formations changes



EG-30: AI for fault detection

Aim:

Investigate the feasibility of AI technics for fault detection on-board aerospace vehicles. The current state of practice generally implies a dedicated algorithm (a.k.a. monitoring) to detect a specific fault, and does not rely on AI technics. A more precise objective of the EG is to investigate AI technics that allow to identify the nominal domain of a specific sensor and so to detect any abnormal behaviour once the sensor measurement goes outside its nominal region.

Status:

- Pilot paper available, October 2021
- List of interested partners: Airbus, FOI, Cira, Onera, DLR, Saab
- Chairman: Philippe Goupil (Airbus)
- EG is active, kick-off meeting in April 2022
- Start of AG: in 2023

FOI: Karin Kraft
CIRA: Gabriella Gigante
ONERA: Gustav ÖMAN-LUNDIN
DLR: Bernd Korn
SaaB: Peter Rosander
Airbus ADS: Thomas Köhler
Airbus Commercial Aircraft:
Philippe Goupil

Thank you for your attention